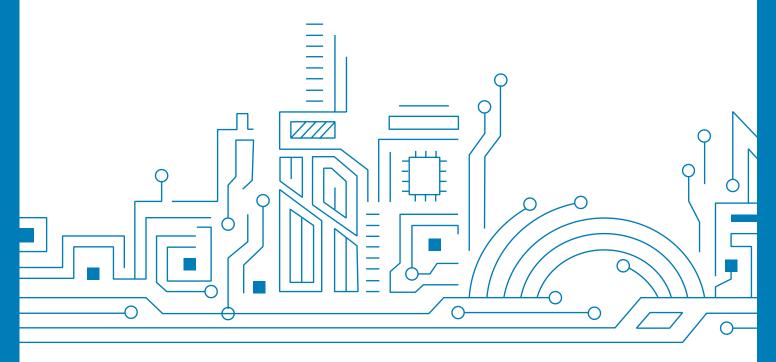


# Multi-Band GNSS Standard Precision Positioning Module

## TAU1201/TAU1204

Datasheet V1.4





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## **About the Document**

#### ■ Basic info

Document applies to	TAU1201, TAU1204
Document type	Datasheet
Revision and date	V1.4/2021-07
Product status	Mass production

#### ■ Product status description

	•						
In development	objective specification. Revision may be released in later status.						
Engineering sample Product specifications tested on early. Revision may be released in late							
Preliminary	Product specifications come from small production. Revision may be released in						
	later status.						
Mass production	Final product specification to mass market.						



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#### 1 SYSTEM OVERVIEW

#### 1.1 Overview

TAU1201/TAU1204 is a high-performance dual-frequency GNSS positioning module, which is based on the state of the art CYNOSURE III architecture. It supports GPS, BeiDou, Galileo, GLONASS, NAVIC/IRNSS, and QZSS.

TAU1201/TAU1204 integrates efficient power management architecture, while providing high precision, high sensitivity and low power consumption GNSS solutions which make it suitable for navigation applications on automotive and consumer electronics navigation, as well as fleet management.

#### 1.2 Features

- · Supports all civil GNSS systems
- Supports BDS-3 signal: B2a
- Concurrent reception of L1 and L5 band signals
- Sub-meter position accuracy; superior in multi-path mitigation and lower noise in city valley
- Smart jammer detection and suppression
- Highly integrated module, the best cost-effective high precision solution
- Supports single IRNSS mode (TAU1204)

#### Table 1 TAU1201/TAU1204

	GNSS			Features			Interface			Accuracy		Grade		е							
Product	Band (S/D/T)	GPS	BDS	GLONASS	Galileo	IRNSS	Built-in LNA	Programmable (flash)	Data logging	D-GNSS	Oscillator	UART	12C	USB	SPI	Meter	Sub-meter	Centimeter	Standard	Professional	Automotive
TAU1201-1216A00	D	•	•	•	•		•	•	•	•	Т	•	0	0	0		•		•		
TAU1204-1216A00	D	•	•		•	•	•	•	•	•	Т	•	0	0	0		•		•		

T= TCXO

 $\circ$ =Supported upon request with special FW

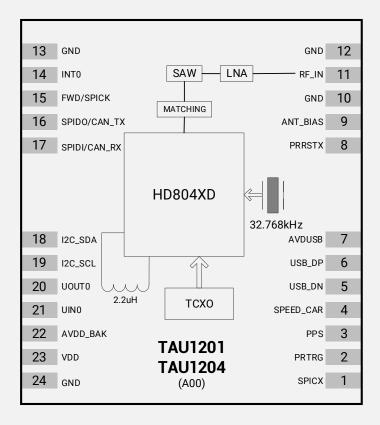
#### 1.3 Module Photo



**Figure 1 TAU1201/TAU1204** 



## 1.4 Block Diagram



**Figure 2 TAU1201/TAU1204** 

## 1.5 Performance Specifications

**Table 2 Performance specifications** 

Parameter	Specifications	Specifications					
GNSS Tracking Channels	40						
		GPS/QZSS: L1C/A, L5C					
	TALI1201	BDS: B1I, B2a					
	TAU1201	GLONASS: L10F					
CNICC Decention		Galileo: E1, E5a					
GNSS Reception		GPS/QZSS: L1C/A, L5C					
	TALI1204	BDS: B1I, B2a					
	TAU1204	Galileo: E1, E5a					
		IRNSS: L5					
Update Rate	Maximum 10Hz						
Position accuracy <sup>[1]</sup>	GNSS	<1m CEP					
Valacity & Time a coursey	GNSS	0.1m/s CEP					
Velocity & Time accuracy	1PPS	20ns					
Time to First Fix(TTFF)	Hot start	1s					



Parameter	Specifications					
	Cold start	32s				
	Cold start	-148dBm				
O Minite	Hot start	-155dBm				
Sensitivity	Reacquisition	-158dBm				
	Tracking	-162dBm				
On a ratio a limait	Velocity	515m/s				
Operating limit	Altitude	18,000m				
Safety supervision	Antenna short circuit p	rotection and open circuit detection				
	UART	1				
Carial intantan	USB <sup>[2]</sup>	1				
Serial interface	SPI <sup>[2]</sup>	1				
	I2C <sup>[2]</sup> 1					
	NMEA 0183 Protocol Ver. 4.0/4.1					
Protocol	RTCM 3.0/3.2/2.3/2.4x <sup>[3]</sup>					
	Cynosure GNSS Receiv					
	Main voltage	2.0 ~ 3.6V				
Operating condition	Digital I/O voltage	1.8 ~ 3.6V				
	Backup voltage	1.8 ~ 3.6V				
	On anating manda	GPS+QZSS L1 band: 22mA@3.3V				
Power consumption	Operating mode	GNSS L1+L5 band: 41mA@3.3V				
	Standby mode	12uA				
Operating temperature	-40°C ~ +85°C					
Storage temperature	-40°C ~ +85°C					
Package	12.2mm*16.0mm*2.4r	nm stamp hole				
Certification	RoHS & REACH					

<sup>\* [1]</sup> Open sky, dual band, demonstrated with a good external LNA

<sup>\* [2]</sup> Supported upon request with special FW.

<sup>\* [3]</sup> RTCM 2.3/2.4x are supported upon request with special FW.



## **2 PIN DESCRIPTION**

13	GND	GND	12
14	INT0	RF_IN	11
15	FWD/SPICK	GND	10
16	SPIDO/CAN_TX	ANT_BIAS	9
17	SPIDI/CAN_RX	PRRSTX	8
	TAU1201 TAU1204		
18	I2C_SDA	AVDUSB	7
19	I2C_SCL	USB_DP	6
20	UOUT0	USB_DN	5
21	UIN0	SPEED_CAR	4
22	AVDD_BAK	PPS	3
23	VDD	PRTRG	2
24	GND	SPICX	1*

<sup>\*</sup> Pin 1 aligns to the circular hole on module cover.

Figure 3 Pin assignment (top view)

Table 3 Detailed pin descriptions

Function	Symbol	No.	I/O	Description
Power	VDD	23	Power	Main supply input.
	GND	10, 12, 13, 24	VSS	Ground
	AVDD_BAK	22	Power	Backup supply input.
	AVDUSB	7 Power		USB power input. To use the USB interface, connect this pin to 3.0-3.6V.
Antenna	RF_IN	11	I	RF signal input. Use a controlled impedance of $50\Omega$ for the routing from RF_IN pin to the antenna or the antenna connector.
	ANT_BIAS	9	0	RF section output voltage. Used to power the external active antenna.
UART	UOUT0	20	0	UART0 serial data output.
UARI	UIN0	21	I	UART0 serial data input.
LIOD[1]	USB_DN	5	I/O	USB I/O line. USB bidirectional communication
USB <sup>[1]</sup>	USB_DP	6	I/O	pin. Leave it floating if not used.
	SPICX	1	0	SPI chip select. Leave it floating if not used.
SPI <sup>[1]</sup>	FWD/SPICK	15	0	SPI clock. Leave it floating if not used.
	SPIDO/CAN_TX	16	0	SPI data or CAN data output. Leave it floating if



				not used
	SPIDI/CAN_RX	17	I	SPI data or CAN data input. Leave it floating if not used
I2C <sup>[1]</sup>	I2C_SDA	18	I/O	I <sup>2</sup> C data. Leave it floating if not used
12017	I2C_SCL	19	I/O	I <sup>2</sup> C clock. Leave it floating if not used
	PRTRG	2	I	Mode selection, or the trigger input in deep sleep mode to wake up the system
	PRRSTX	8	I	External reset, low active
Custom	PPS	3	0	Time pulse output (PPS)
System	SPEED_CAR <sup>[1]</sup>	4	I	Speed pulse. Leave it floating if not used. Default GPIO.
	INT0	14	I	External interrupt. Leave it floating if not used. Default GPIO.

<sup>\* [1]</sup> Supported upon request with special FW.



### 3 ELECTRICAL CHARACTERISTICS

## 3.1 Absolute Maximum Rating

**Table 4 Absolute rating** 

Symbol	Parameter	Min.	Max.	Unit
VDD	Power input for the main power domain	-0.5	3.63	V
AVDUSB	USB supply voltage	-0.5	3.63	V
AVDD_BAK	Power input for the backup power domain	-0.5	3.63	V
VI <sub>max</sub>	Voltage input of I/O pin	-0.5	3.63	V
T <sub>storage</sub>	Storage temperature	-40	85	°C
T <sub>solder</sub>	Solder reflow temperature	-	260	°C

#### 3.2 IO Characteristics

#### 3.2.1 PRRSTX and PRTRG

#### **Table 5 PRRSTX and PRTRG**

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
I <sub>IZ</sub>	Input leakage current				+/-1	uA
$V_{IH}$	Input high voltage		AVDD_BAK *0. 7		AVDD_BAK	V
$V_{IL}$	Input low voltage		0		AVDD_BAK *0.3	V
Ci	Input capacitance			-	10	pF
R <sub>PU</sub>	Pull-up resistance		18		84	kΩ

#### 3.2.2 USB I/O

#### Table 6 USB signal

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
I <sub>IZ</sub>	Input leakage current				+/-10	uA
V <sub>IH</sub>	Input high voltage		AVDUSB*0.9		AVDUSB	٧
V <sub>IL</sub>	Input low voltage		0	-	AVDUSB*0.1	٧
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> =10 mA, AVDUSB=3.3V	2.35			٧
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> =10 mA, AVDUSB=3.3V			0.5	٧
R <sub>PUIDEL</sub>	Pull-up resistance, idle state		0.9		1.575	kΩ
R <sub>PUACTIVE</sub>	Pull-up resistance, active state		1.425		3.09	kΩ

#### **3.2.3** Others

#### **Table 7 Others**

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
I <sub>IZ</sub>	Input leakage current				+/-1	uA
V <sub>IH</sub>	Input high voltage		VDD*0.7		VDD	V
V <sub>IL</sub>	Input low voltage		0		VDD*0.3	V



V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> =11.9 mA, VDD=3.3V	2.64			V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> =7.9 mA, VDD=3.3V		-	0.4	V
Ci	Input capacitance				11	pF
R <sub>PU</sub>	Pull-up resistance		35		84	kΩ

#### 3.3 DC Characteristics

#### **3.3.1** Operating Conditions

**Table 8 Operating conditions** 

Symbol	Parameter	Min.	Тур.	Max.	Unit
VDD	Main voltage	2.0	3.3	3.6	V
AVDUSB	USB supply voltage	3.0	3.3	3.6	V
AVDD_BAK	Power input for the backup power domain	1.8	3.3	3.6	V
I <sub>ANT_BIAS</sub>	ANT_BIAS output current	-	-	35	mA
V <sub>ANT_BIAS</sub>	ANT_BIAS output voltage	-	VDD-0.2	-	V
ICC <sub>max</sub>	Maximum operating current @VDD		-	200	mA
T <sub>env</sub>	Operating temperature	-40	-	85	°C

#### **3.3.2** Power Consumption

#### **Table 9 Power consumption**

Symbol	Parameter	Measure pin	Тур.	Unit
I <sub>CCRX1</sub>	Average tracking current (GPS+QZSS, L1 only)	VDD <sup>[1]</sup>	22	mA
I <sub>CCRX2</sub>	Average tracking current (GNSS, L1+L5)	VDD [1]	41	mA
I <sub>CCDBM</sub>	Standby mode	AVDD_BAK [2]	12	uA

<sup>\* [1]</sup> Condition: VDD=3.3V@Room Temperature; All Pins Open.

<sup>\* [2]</sup> Condition: AVDD\_BAK=3.3V@Room Temperature; All Pins Open.



#### 4 HARDWARE DESCRIPTION

#### 4.1 Connecting Power

TAU1201/TAU1204 positioning module has two power supply pins: VDD and AVDD\_BAK. The main power is supplied through the VDD pin, and the backup power is supplied through the AVDD\_BAK pin. In order to ensure the positioning performance, please control the ripple of the module power supply. It is recommended to use the LDO above 200mA.

If the power for VDD pin is off, the real-time clock (RTC) and battery backed RAM (BBR) will be supplied through the AVDD\_BAK pin. Thus, orbit information and time can be maintained and will allow a Hot or Warm start. If no backup battery is connected, the module will perform a cold start at every power-up if no aiding data are sent to the receiver.

Note: If no backup supply is available, connect the AVDD\_BAK pin to VDD or leave it floating.

#### 4.2 Power on/off Sequence

TAU1201/TAU1204 has two independent power domains (backup and main domain). In data backup mode, main power supply can be completely shut down for further power reduction for ultra-low power application.

#### 4.2.1 Initial system power on

When both backup and main supply power on from their off state, external reset (PRRSTX) must be active and hold more than 5ms after both backup supply and main supply reach the minimum operating voltage. Initial system power on sequence is illustrated in Figure 4.

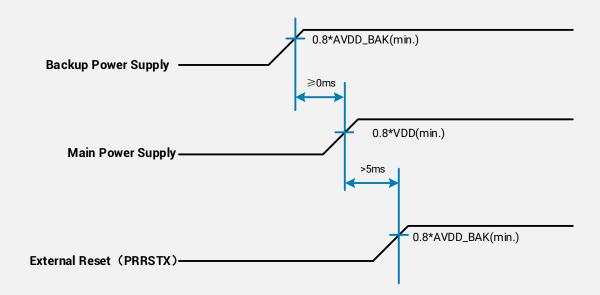


Figure 4 Initial system power on sequence



#### 4.2.2 Main power supply off/on in application

If application intends to shut down main power supply (VDD) while keep backup power supply (AVDD\_BAK) alive to save backup data, the following rules should be applied:

External reset (PRRSTX) must be active when main power supply is under power off. In this case, external reset must be hold active more than 5ms after main power supply resumes to minimum operating voltage. Main power on sequence in application is illustrated in Figure 5.

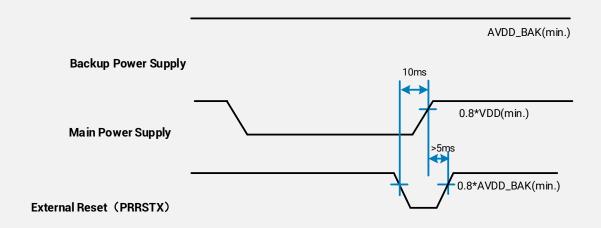


Figure 5 Main power on sequence

#### 4.3 Antenna Design

There is built-in LNA and SAW in the GNSS module. It is recommended to use an active antenna with gain less than 36dB and the noise figure less than 1.5dB.

The module has built-in short circuit detection and open circuit detection function, which can detect the status of normal connection, and send out antenna status prompt message in NMEA data.

- Short circuit protection
  - » The module includes internal short circuit antenna detection. Once an overcurrent is detected at the ANT\_BIAS port, the module will restrict current output automatically to protect from damages.
- Open circuit detection
  - » The module can detect an open circuit in the antenna. Users can judge it from antenna status messages.

Table 10 ANT\_BIAS current range and antenna status

Antenna status	Status output	ANT_BIAS current range
Open circuit	OPEN	0< ANT_BIAS ≤ 1mA
Regular circuit or open circuit	OK or OPEN	1mA< ANT_BIAS ≤ 2mA
Regular circuit	OK	2mA< ANT_BIAS ≤ 40±5mA <sup>[1]</sup>
Short circuit	SHORT	40±5mA <sup>[1]</sup> < ANT_BIAS < 55mA

 <sup>[1] ±5</sup>mA are differences between product batches.

#### TIPs:

1. Pulse width of the minimum detectable overshoot current should be more than 10uS.



- NMEA message of antenna status output:
- OPEN: \$GNTXT,01,01,01,ANT\_OPEN\*40
- OK: \$GNTXT,01,01,01,ANT\_OK\*50
- SHORT: \$GNTXT,01,01,01,ANT\_SHORT\*06

#### 4.4 Reset and Mode Control

The operation mode of GNSS module is controlled by PRRSTX (nRESET) and PRTRG (BOOT) pin. While the module works in normal operation, leave PRRSTX and PRTRG pins floating if there is no upgrading or reset demands, or others.

- Keep PRTRG pin floating during system power-up or the external reset (PRRSTX from low to high), and the module will enter **User Normal Mode**.
- When the module powers up or PRRSTX from low to high, the module will execute an external
  reset. (If the power for AVDD\_BAK is always on, the external reset will not affect the ephemeris
  data in the backup domain)
- Drive PRTRG pin to low or connect PRTRG to GND directly (not by pull-down resistance) during
  system power-up or the external reset (PRRSTX from low to high), and the system enters
  BootROM Command Mode at PRTRG pin being released from low to floating state, and ready for
  firmware upgrading command.
- When connecting PRRSTX and PRTRG to any host IO, DO NOT use the pull-up or pull-down resistance.

#### 4.5 Default Serial Interfaces

Table 11 Default message

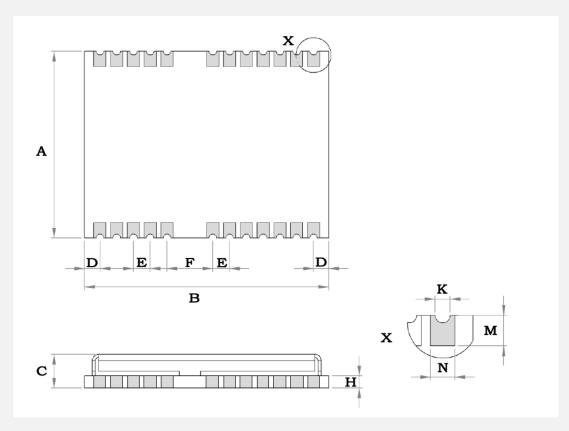
Interface	Settings
	115200 baud, 8 data bits, no parity bit, 1 stop bit
LIADT output	Configured to transmit both NMEA and HD Binary protocols, but only the following
UART output	NMEA (and no HD Binary sentence) messages have been activated at start-up:
	GGA, GSA, GSV, RMC, ZDA, TXT-ANT
	115200 baud, 8 data bits, no parity bit, 1 stop bit, autobauding disabled
LIADT input	Automatically accepts following protocols without need of explicit configuration:
UART input	HD binary sentence, NMEA, RTCM
	The GNSS receiver supports interleaved HD binary and NMEA messages.
Timepluse (1Hz Nav)	1 pulse per second, synchronized at rising edge, pulse length 100ms

Refer to GNSS\_Protocol\_Specification for information about other settings.

When the module is applied to the specific application, users can shut off the main power in order to further reduce the power consumption. To avoid the high level in serial interface influencing the normal operation, it is highly suggested to cut off the serial port when shut off the main power. Otherwise, please set the serial port to input mode or high impedance state with pull-down resistor.



## 5 MECHANICAL SPECIFICATION



**Figure 6 Dimensions** 

**Table 12 Dimensions** 

Symbol	Min.(mm)	Typ.(mm)	Max.(mm)
Α	12.0	12.2	12.4
В	15.8	16.0	16.2
С	2.2	2.4	2.6
D	0.9	1.0	1.3
E	1.0	1.1	1.2
F	2.9	3.0	3.1
Н		0.8	
K	0.4	0.5	0.6
М	0.8	0.9	1.0
N	0.7	0.8	0.9



#### **6 REFERENCE DESIGN**

## 6.1 Minimal Design

This is a minimal design for TAU1201/TAU1204 GNSS module as below. The 82nH inductor is used only when an active antenna is connected, and no need with a passive antenna. The characteristic impedance from RF\_IN pin to the antenna connector should be  $50\Omega$ .

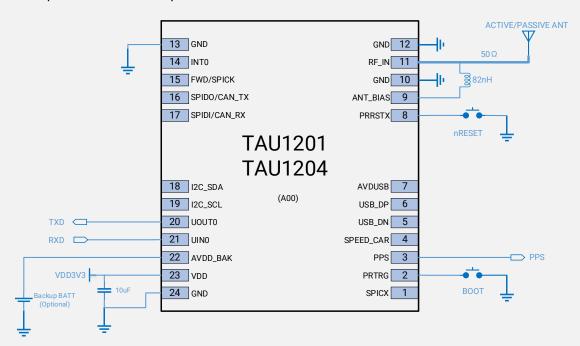
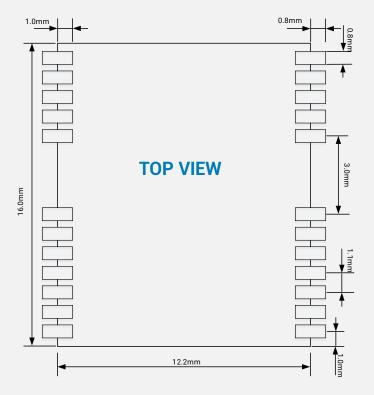


Figure 7 Minimal application diagram



## **6.2** PCB Footprint Reference



**Figure 8 PCB Footprint Reference** 

## **6.3** Layout Notes

- (1) A decoupling capacitor should be placed close to VDD pin of the module, and the width of power routing should be more than 0.5mm.
- (2) The width of RF routing between RF port to antenna interface should be wider than 0.2mm. The characteristic impedance of RF routing between RF port to antenna interface should be controlled to  $50\Omega$ .
- (3) It is recommended that the routing from RF port to antenna interface refers to the second layer, and no routing are recommended on the layer.
- (4) Do not place the module close to any EMI source, like antenna, RF routing, DC/DC or power conductor, clock signal or other high-frequency switching signal, etc.



#### 7 REFLOW SOLDERING

**Table 13 Reflow profile features** 

Profile Feature	Pb-Free Assembly
Preheat/Soak	
Temperature Min (T <sub>smin</sub> )	150 °C
Temperature Max (T <sub>smax</sub> )	200 °C
Time (ts) from (Tsmin to Tsmax)	60-120s
Ramp-up rate (TL to Tp)	3 °C/second max.
Liquidous temperature (TL)	217 °C
Time (t <sub>L</sub> ) maintained above T <sub>L</sub>	60-150s
Peak package body temperature (T <sub>p</sub> )	must not exceed the Classification temp $T_c^{[1]}$
Time (t <sub>p</sub> )* within 5 °C of the specified classification	30* seconds <sup>[2]</sup>
temperature (Tc)	50" Seconds · /
Ramp-down rate (Tp to TL)	6 °C/second max.
Time 25 °C to peak temperature	8 minutes max.

- \* [1] T<sub>c</sub>=260°C.
- \* [2] The time above 255 °C must not exceed 30 seconds.

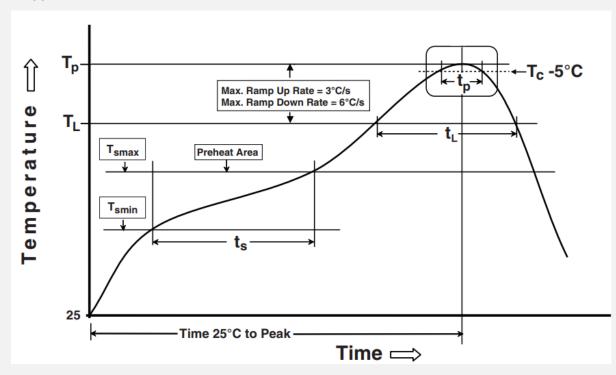


Figure 9 Reflow soldering profile (Refer to IPC/JEDEC J-STD-020E)



#### 8 PRODUCT PACKAGING AND HANDLING

#### 8.1 Packaging

#### 8.1.1 Packaging Notes

TAU1201/TAU1204 GNSS module is a Moisture Sensitive Device (MSD) and Electrostatic Sensitive Device (ESD). During the packing and shipping, it is strictly required to take appropriate MSD handling instructions and precautions. The table below shows the general packing hierarchy for the standard shipment.

**Table 14 Packing hierarchy** 

Module	Reel	Sealed bag	Shipping carton

#### 8.1.2 Tape and Reel

The TAU1201/TAU1204 modules are delivered as hermetically sealed, reeled tapes in order to enable efficient production, production lot set-up and tear-down. The figure below shows the tape dimensions.

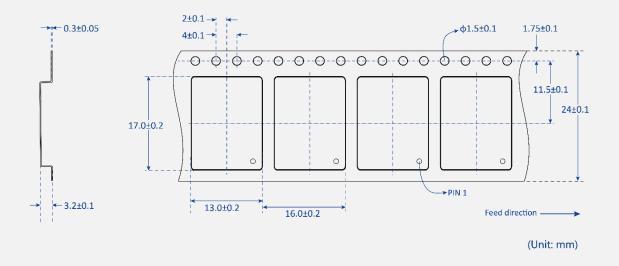


Figure 10 Tape dimensions



TAU1201/TAU1204 are deliverable in quantities of 1000pcs on a reel. The figure below shows the dimensions of reel for TAU1201/TAU1204.

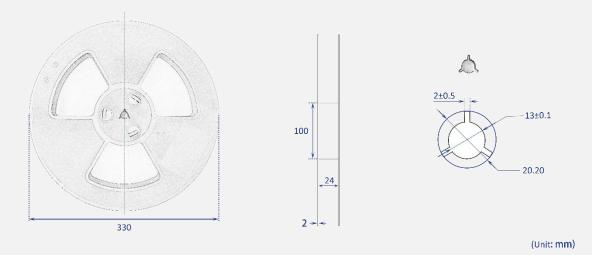


Figure 11 Reel dimensions

#### 8.1.3 Shipment Packaging

The reels of TAU1201/TAU1204 modules are packed in the sealed bags and shipped by shipping cartons. Up to five sealed bags (5000pcs in total) can be packed in one shipping carton.

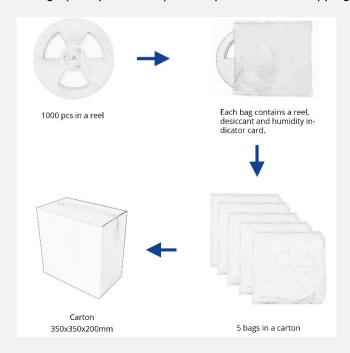


Figure 12 Packaging

## 8.2 Storage

In order to prevent moisture intake and protect against electrostatic discharge, TAU1201/TAU1204 is packaged together with a humidity indicator card and desiccant to absorb humidity.



#### 8.3 ESD Handling

#### **8.3.1** ESD Handling Precautions

TAU1201/TAU1204 module which contains highly sensitive electronic circuitry is an Electrostatic-sensitive Device (ESD). Observe precautions for handling! Failure to observe these precautions may result in severe damage to the GNSS module!

- Before mounting an antenna patch, connect ground of the device.
- When handling the RF pin, do not come into contact with any charged capacitors and be careful when contacting materials that can develop charges (e.g. patch antenna ~10 pF; coax cable ~50 80 pF/m; soldering iron ...)
- To prevent electrostatic discharge through the RF input, do not touch any exposed antenna area. If there is any risk that such exposed antenna area is touched in non ESD protected work area, implement proper ESD protection measures in the design.
- When soldering RF connectors and patch antennas to the receiver's RF pin, make sure to use an ESD safe soldering iron (tip).



#### **8.3.2** ESD Protection Measures

The GNSS positioning module is sensitive to static electricity. Whenever handling the module, particular care must be exercised to reduce the risk of electrostatic charges. In addition to standard ESD safety practices, the following measures should be taken into account.

- Adds ESD Diodes to the RF input part to prevent electrostatics discharge.
- Do not touch any exposed antenna area.
- Adds ESD Diodes to the UART interface.

#### 8.3.3 Moisture Sensitivity Level

The Moisture Sensitivity Level (MSL) of the GNSS module is MSL4.



#### 9 LABELING AND ORDERING INFORMATION

Labeling and ordering information help customers get more about Allystar products.

## 9.1 Labeling

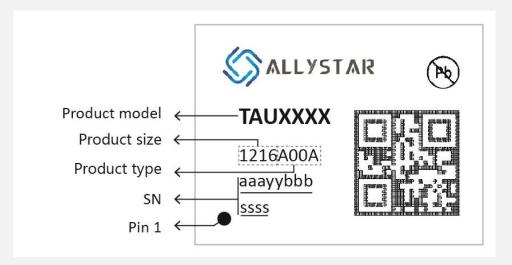


Table 15 Labeling content

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Symbol	Explanation	Instance		
TAUXXXX	Product model	TAU1201		
10164004	1216 represents the product size.	1016 4 0 0		
	A00 means the product type.	1216A00		
1216A00A	Second A refers to sales area code. Different code for	E (for Europe market)		
	different sales area.	E (for Europe market)		
aaayybbbssss	Serial number	385190010001		

## 9.2 Ordering info

**Table 16 Ordering codes** 

Ordering No.	Product
TAU1201-1216A00E	Concurrent GNSS LCC Module, TCXO, ROM, GLONASS, 12.2*16mm, 1000
1AU1201-1210AUUE	pieces/reel, Europe market
TAU1201-1216A00H	Concurrent GNSS LCC Module, TCXO, ROM, GLONASS, 12.2*16mm, 1000
1AU1201-1210AUUN	pieces/reel, India market
TAU1201-1216A00R	Concurrent GNSS LCC Module, TCXO, ROM, GLONASS, 12.2*16mm, 1000
1AU1201-1210AUUK	pieces/reel, Russia market
TAU1204-1216A00E	Concurrent GNSS LCC Module, TCXO, ROM, IRNSS, 12.2*16mm, 1000
1AU1204-1210AUUE	pieces/reel, Europe market
TAU1204-1216A00H	Concurrent GNSS LCC Module, TCXO, ROM, IRNSS, 12.2*16mm, 1000
1AU1204-1210AUUN	pieces/reel, India market
TAU1204-1216A00R	Concurrent GNSS LCC Module, TCXO, ROM, IRNSS, 12.2*16mm, 1000
1AU1204-1210AUUR	pieces/reel, Russia market



## 10 RELATED DOCUMENTS

- [1] Satrack User Manual
- [2] Allystar Common Commands
- [3] GNSS\_Protocol\_Specification

## 11 REVISION HISTORY

Revision	Date	Author	Status / Comments
V1.0	2019.08	Vita Wu	First released
V1.1	2019.12	Vita Wu	Updates the packaging info;
			Update Section 6;
			Adds PCB packaging;
			Updates LNA built-in;
			Updates power consumption;
			Updates antenna gain in Section 4.2;
V1.2	2020.07	Vita Wu	Adds GNSS raw data output support.
			Adds ANT_BIAS parameters.
			Updates C00 design.
			Contents update
V1.3	2020.12	Vita Wu	Deletes SBAS support.
			Clarifies power on/off sequence.
			Improves AVDD_BAK pin connection description in
			Section 4.1.
			Improves mechanical specification.
			Updates layout notes in Section 6.3.
			Deletes 1K resistor in the minimal design diagram.
			Updates MSL.
			Localization.
			Updates description about short circuit protection
V1.4	2021-07	Vita Wu	Adds labeling and ordering info.
			Details default settings.
			Adds related document list.
			Adds document info section.
			Removes C00 design.
			Updates main voltage range to be 2.0V~3.6V.





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